

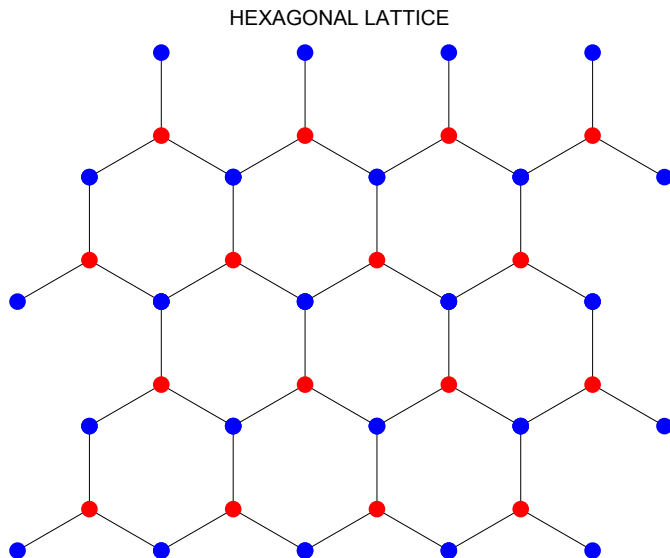
Random Walks on a Hexagonal Lattice

Nicholas Wheeler

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Introduction

This work is motivated by my 2nd conversation with Sina Zeytinoglu (whose previous visit motivated me to write "Iteration Techniques" (23 November 2011)). Here is a hexagonal lattice:



Notice that this is what I have been motivated elsewhere to call a "blinking" design: the node on which the walker stands changes color with each step.

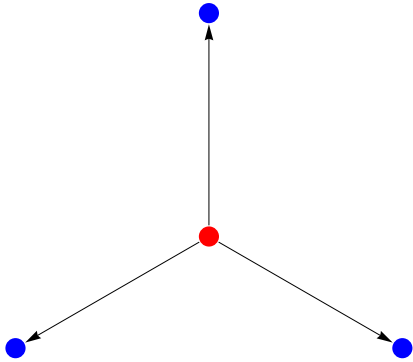
The following vectors describe the steps (of unit length) available to a walker who stands on ●

$$R_1 = \left\{ \cos\left[\frac{\pi}{2}\right], \sin\left[\frac{\pi}{2}\right] \right\};$$

$$R_2 = \left\{ \cos\left[\frac{\pi}{2} - 4 \frac{2\pi}{12}\right], \sin\left[\frac{\pi}{2} - 4 \frac{2\pi}{12}\right] \right\};$$

$$R_3 = \left\{ \cos\left[\frac{\pi}{2} - 8 \frac{2\pi}{12}\right], \sin\left[\frac{\pi}{2} - 8 \frac{2\pi}{12}\right] \right\};$$

```
RedOptions = Graphics[{{Red, PointSize[0.05], Point[{0, 0]}},
  {Blue, PointSize[0.05], Point[R1]},
  {Blue, PointSize[0.05], Point[R2]},
  {Blue, PointSize[0.05], Point[R3]},
  {Arrow[{{0, 0}, R1}, .05]},
  {Arrow[{{0, 0}, R2}, .05]},
  {Arrow[{{0, 0}, R3}, .05]}}
```



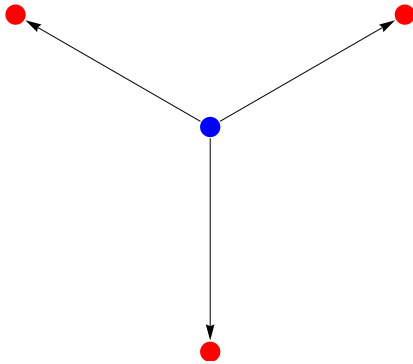
while these vectors—the negatives of the preceding vectors—describe the unit steps available to a walker who stands momentarily on ●:

$$B_1 = -R_1;$$

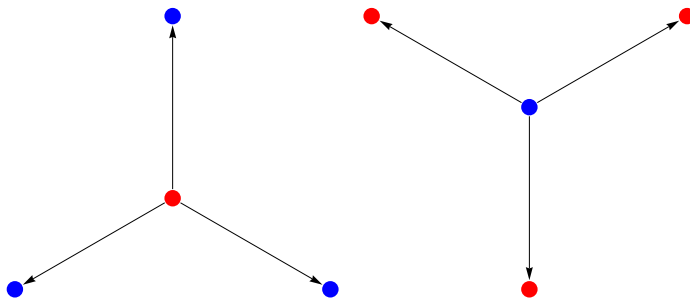
$$B_2 = -R_2;$$

$$B_3 = -R_3;$$

```
BlueOptions = Graphics[{{Blue, PointSize[0.05], Point[{0, 0]}},
  {Red, PointSize[0.05], Point[B1]},
  {Red, PointSize[0.05], Point[B2]},
  {Red, PointSize[0.05], Point[B3]},
  {Arrow[{{0, 0}, B1], .05}},
  {Arrow[{{0, 0}, B2], .05}},
  {Arrow[{{0, 0}, B3], .05}}}]
```



```
GraphicsArray[{{RedOptions, BlueOptions}}
```



"By hand" construction of a 30-step hexagonal walk

The following multiple command serves to construct 30-step hexagonal walks "by hand":

```

S1 = RandomChoice[{R1, R2, R3}] ;
S2 = RandomChoice[{B1, B2, B3}] ;
S3 = RandomChoice[{R1, R2, R3}] ;
S4 = RandomChoice[{B1, B2, B3}] ;
S5 = RandomChoice[{R1, R2, R3}] ;
S6 = RandomChoice[{B1, B2, B3}] ;
S7 = RandomChoice[{R1, R2, R3}] ;
S8 = RandomChoice[{B1, B2, B3}] ;
S9 = RandomChoice[{R1, R2, R3}] ;
S10 = RandomChoice[{B1, B2, B3}] ;
S11 = RandomChoice[{R1, R2, R3}] ;
S12 = RandomChoice[{B1, B2, B3}] ;
S13 = RandomChoice[{R1, R2, R3}] ;
S14 = RandomChoice[{B1, B2, B3}] ;
S15 = RandomChoice[{R1, R2, R3}] ;
S16 = RandomChoice[{B1, B2, B3}] ;
S17 = RandomChoice[{R1, R2, R3}] ;
S18 = RandomChoice[{B1, B2, B3}] ;
S19 = RandomChoice[{R1, R2, R3}] ;
S20 = RandomChoice[{B1, B2, B3}] ;
S21 = RandomChoice[{R1, R2, R3}] ;
S22 = RandomChoice[{B1, B2, B3}] ;
S23 = RandomChoice[{R1, R2, R3}] ;
S24 = RandomChoice[{B1, B2, B3}] ;
S25 = RandomChoice[{R1, R2, R3}] ;
S26 = RandomChoice[{B1, B2, B3}] ;
S27 = RandomChoice[{R1, R2, R3}] ;
S28 = RandomChoice[{B1, B2, B3}] ;
S29 = RandomChoice[{R1, R2, R3}] ;
S30 = RandomChoice[{B1, B2, B3}] ;

SuccessivePositions = Table[Pk =  $\sum_{j=1}^k S_j$ , {k, 1, 30}] ;

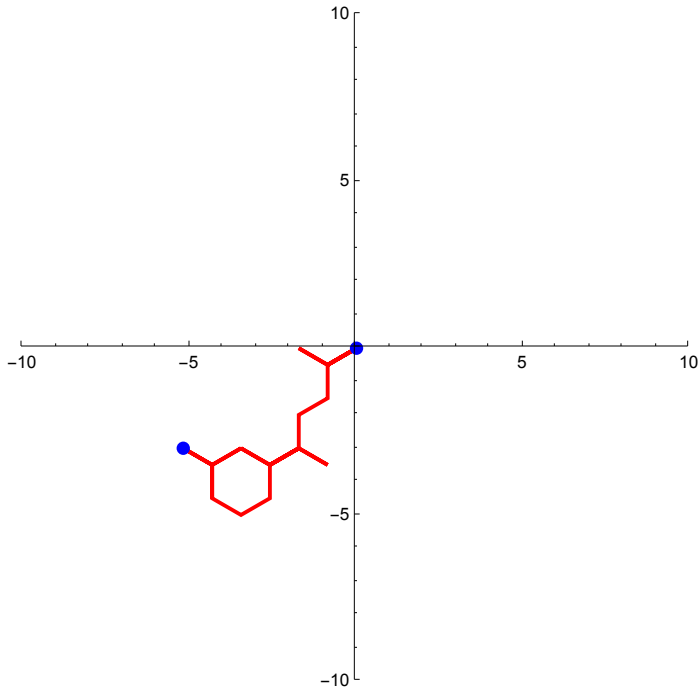
HexagonalWalk = Prepend[SuccessivePositions, {0, 0}] ;

Walk30 = ListLinePlot[HexagonalWalk, AspectRatio → Automatic, AxesOrigin → {0, 0},
  PlotRange → {{-10, 10}, {-10, 10}}, PlotStyle → {Thick, Red}] ;

Endpoints30 = Graphics[{{Blue, PointSize[0.02], Point[{0, 0]}},
  {Blue, PointSize[0.02], Point[Last[HexagonalWalk]]}}] ;

Show[{Walk30, EndPoints30}]

```



Many repetitions later, I am surprised by the frequency with which the walker doubles back, retraces previous steps.

Automating the construction of such walks

I can't get the `Nest` command to construct *alternating* RBRBRBRB sequences, so adopt a relatively clumsy procedure of which I provide first a sketch:

```
A = Table[Transpose[
  {{RandomChoice[{R1, R2, R3}], RandomChoice[{B1, B2, B3}]}}], {k, 1, 10}]
```

```
B = Table[MatrixPower[ $\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ , k].A[[k]], {k, 1, 10}]
```

```
Steps = Table[Flatten[B[[k]][[1]][[1]], {k, 1, 10}]
```

```
{{{R3}, {B3}}, {{R3}, {B2}}, {{R2}, {B2}}, {{R1}, {B3}}, {{R1}, {B3}},
  {{R3}, {B2}}, {{R3}, {B1}}, {{R3}, {B1}}, {{R2}, {B1}}, {{R2}, {B2}}}
```

```
{{{B3}, {R3}}, {{R3}, {B2}}, {{B2}, {R2}}, {{R1}, {B3}}, {{B3}, {R1}},
  {{R3}, {B2}}, {{B1}, {R3}}, {{R3}, {B1}}, {{B1}, {R2}}, {{R2}, {B2}}}
```

```
{B3, R3, B2, R1, B3, R3, B1, R3, B1, R2}
```

In the context at hand the objects R1, R2, ..., B3 are 2-vectors. I find that *Mathematica* objects to subscripted notation in this context, so I renote my vectors:

$$R1 = \left\{ \cos\left[\frac{\pi}{2}\right], \sin\left[\frac{\pi}{2}\right] \right\};$$

$$R2 = \left\{ \cos\left[\frac{\pi}{2} - 4 \frac{2\pi}{12}\right], \sin\left[\frac{\pi}{2} - 4 \frac{2\pi}{12}\right] \right\};$$

$$R3 = \left\{ \cos\left[\frac{\pi}{2} - 8 \frac{2\pi}{12}\right], \sin\left[\frac{\pi}{2} - 8 \frac{2\pi}{12}\right] \right\};$$

$$B1 = -R1;$$

$$B2 = -R2;$$

$$B3 = -R3;$$

Step 1 of the procedure sketched above produces

A = Table[

Transpose[{{RandomChoice[{R1, R2, R3}], RandomChoice[{B1, B2, B3}]}}], {k, 1, 10}]

$$\begin{aligned} & \left\{ \left\{ \left\{ -\frac{\sqrt{3}}{2}, -\frac{1}{2} \right\} \right\}, \left\{ \left\{ \frac{\sqrt{3}}{2}, \frac{1}{2} \right\} \right\}, \left\{ \{0, 1\} \right\}, \left\{ \{0, -1\} \right\} \right\}, \\ & \left\{ \left\{ \{0, 1\} \right\}, \left\{ \left\{ \frac{\sqrt{3}}{2}, \frac{1}{2} \right\} \right\}, \left\{ \left\{ \frac{\sqrt{3}}{2}, -\frac{1}{2} \right\} \right\}, \left\{ \left\{ -\frac{\sqrt{3}}{2}, \frac{1}{2} \right\} \right\}, \left\{ \{0, 1\} \right\}, \left\{ \left\{ -\frac{\sqrt{3}}{2}, \frac{1}{2} \right\} \right\} \right\}, \\ & \left\{ \left\{ \left\{ \frac{\sqrt{3}}{2}, -\frac{1}{2} \right\} \right\}, \left\{ \left\{ -\frac{\sqrt{3}}{2}, \frac{1}{2} \right\} \right\}, \left\{ \left\{ \frac{\sqrt{3}}{2}, -\frac{1}{2} \right\} \right\}, \left\{ \{0, -1\} \right\} \right\}, \\ & \left\{ \left\{ \{0, 1\} \right\}, \left\{ \{0, -1\} \right\}, \left\{ \left\{ \frac{\sqrt{3}}{2}, -\frac{1}{2} \right\} \right\}, \left\{ \left\{ -\frac{\sqrt{3}}{2}, \frac{1}{2} \right\} \right\}, \left\{ \left\{ \frac{\sqrt{3}}{2}, -\frac{1}{2} \right\} \right\}, \left\{ \{0, -1\} \right\} \right\} \end{aligned}$$

A[[1]]

$$\left\{ \left\{ \left\{ -\frac{\sqrt{3}}{2}, -\frac{1}{2} \right\} \right\}, \left\{ \left\{ \frac{\sqrt{3}}{2}, \frac{1}{2} \right\} \right\} \right\}$$

The matrix $\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ serves still to reverse those vectors

$$\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \cdot \%$$

$$\left\{ \left\{ \left\{ \frac{\sqrt{3}}{2}, \frac{1}{2} \right\} \right\}, \left\{ \left\{ -\frac{\sqrt{3}}{2}, -\frac{1}{2} \right\} \right\} \right\}$$

so we construct

$$B = \text{Table}[\text{MatrixPower}\left[\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, k\right] \cdot A[[k]], \{k, 1, 10\}]$$

$$\begin{aligned} & \left\{ \left\{ \left\{ \frac{\sqrt{3}}{2}, \frac{1}{2} \right\}, \left\{ -\frac{\sqrt{3}}{2}, -\frac{1}{2} \right\} \right\}, \left\{ \{0, 1\}, \{0, -1\} \right\}, \right. \\ & \left\{ \left\{ \frac{\sqrt{3}}{2}, \frac{1}{2} \right\}, \{0, 1\} \right\}, \left\{ \left\{ \frac{\sqrt{3}}{2}, -\frac{1}{2} \right\}, \left\{ -\frac{\sqrt{3}}{2}, \frac{1}{2} \right\} \right\}, \left\{ \left\{ -\frac{\sqrt{3}}{2}, \frac{1}{2} \right\}, \{0, 1\} \right\}, \right. \\ & \left\{ \left\{ \frac{\sqrt{3}}{2}, -\frac{1}{2} \right\}, \left\{ -\frac{\sqrt{3}}{2}, \frac{1}{2} \right\} \right\}, \left\{ \{0, -1\}, \left\{ \frac{\sqrt{3}}{2}, -\frac{1}{2} \right\} \right\}, \\ & \left. \left\{ \{0, 1\}, \{0, -1\} \right\}, \left\{ \left\{ -\frac{\sqrt{3}}{2}, \frac{1}{2} \right\}, \left\{ \frac{\sqrt{3}}{2}, -\frac{1}{2} \right\} \right\}, \left\{ \left\{ \frac{\sqrt{3}}{2}, -\frac{1}{2} \right\}, \{0, -1\} \right\} \right\} \end{aligned}$$

Commands such as these serve to extract the leading member of each vector pair:

$$B[[1]][[1]][[1]]$$

$$B[[2]][[1]][[1]]$$

$$B[[3]][[1]][[1]]$$

$$\left\{ \frac{\sqrt{3}}{2}, \frac{1}{2} \right\}$$

$$\{0, 1\}$$

$$\left\{ \frac{\sqrt{3}}{2}, \frac{1}{2} \right\}$$

We do so, and prepend the zero vector $\{0, 0\}$ so that our walks begin at the origin. We arrive thus as this set of random alternating BRBRBRB steps

$$\text{Steps} = \text{Prepend}[\text{Table}[B[[k]][[1]][[1]], \{k, 1, 10\}], \{0, 0\}]$$

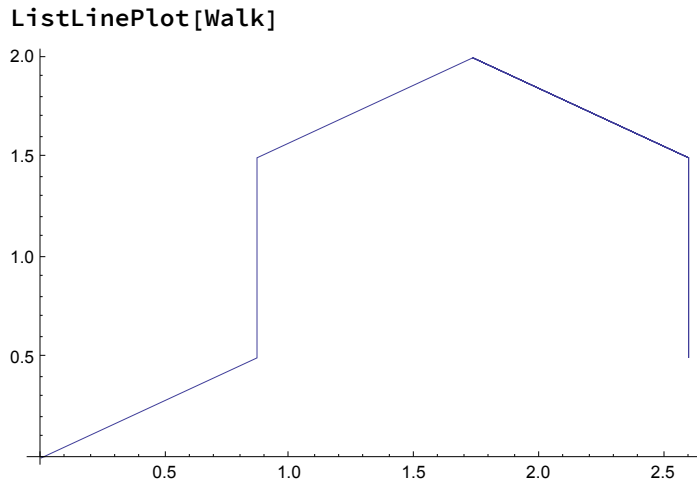
$$\begin{aligned} & \left\{ \{0, 0\}, \left\{ \frac{\sqrt{3}}{2}, \frac{1}{2} \right\}, \{0, 1\}, \left\{ \frac{\sqrt{3}}{2}, \frac{1}{2} \right\}, \left\{ \frac{\sqrt{3}}{2}, -\frac{1}{2} \right\}, \right. \\ & \left. \left\{ -\frac{\sqrt{3}}{2}, \frac{1}{2} \right\}, \left\{ \frac{\sqrt{3}}{2}, -\frac{1}{2} \right\}, \{0, -1\}, \{0, 1\}, \left\{ -\frac{\sqrt{3}}{2}, \frac{1}{2} \right\}, \left\{ \frac{\sqrt{3}}{2}, -\frac{1}{2} \right\} \right\} \end{aligned}$$

which we link together to build up a 10-step walk:

$$\text{Walk} = \text{Table}\left[\sum_{j=1}^k \text{Steps}[[j]], \{k, 1, 11\}\right]$$

$$\begin{aligned} & \left\{ \{0, 0\}, \left\{ \frac{\sqrt{3}}{2}, \frac{1}{2} \right\}, \left\{ \frac{\sqrt{3}}{2}, \frac{3}{2} \right\}, \{\sqrt{3}, 2\}, \left\{ \frac{3\sqrt{3}}{2}, \frac{3}{2} \right\}, \{\sqrt{3}, 2\}, \right. \\ & \left. \left\{ \frac{3\sqrt{3}}{2}, \frac{3}{2} \right\}, \left\{ \frac{3\sqrt{3}}{2}, \frac{1}{2} \right\}, \left\{ \frac{3\sqrt{3}}{2}, \frac{3}{2} \right\}, \{\sqrt{3}, 2\}, \left\{ \frac{3\sqrt{3}}{2}, \frac{3}{2} \right\} \right\} \end{aligned}$$

The walk thus generated looks like this:



We now consolidate those commands to produce at random a 200-step hexagonal walk with a single composite command:


```

A200 = Table[Transpose[
  {{RandomChoice[{R1, R2, R3}], RandomChoice[{B1, B2, B3}]}}], {k, 1, 200}];

B200 = Table[MatrixPower[ $\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ , k].A200[[k]], {k, 1, 200}];

Steps200 = Prepend[Table[B200[[k]][[1]][[1]], {k, 1, 200}], {0, 0}];

Walk200 = Table[ $\sum_{j=1}^k$  Steps200[[j]], {k, 1, 201}];

HexagonalWalk200 =
  ListLinePlot[Walk200, AspectRatio → Automatic, AxesOrigin → {0, 0},
    PlotRange → {{-20, 20}, {-20, 20}}, PlotStyle → {Thick, Red}];

EndPoints200 = Graphics[{{Blue, PointSize[0.02], Point[{0, 0]}},
  {Blue, PointSize[0.02], Point[Last[Walk200]]}}];

Show[{HexagonalWalk200, EndPoints200}, PlotLabel → "200-Step Hexagonal Walk"]

```

