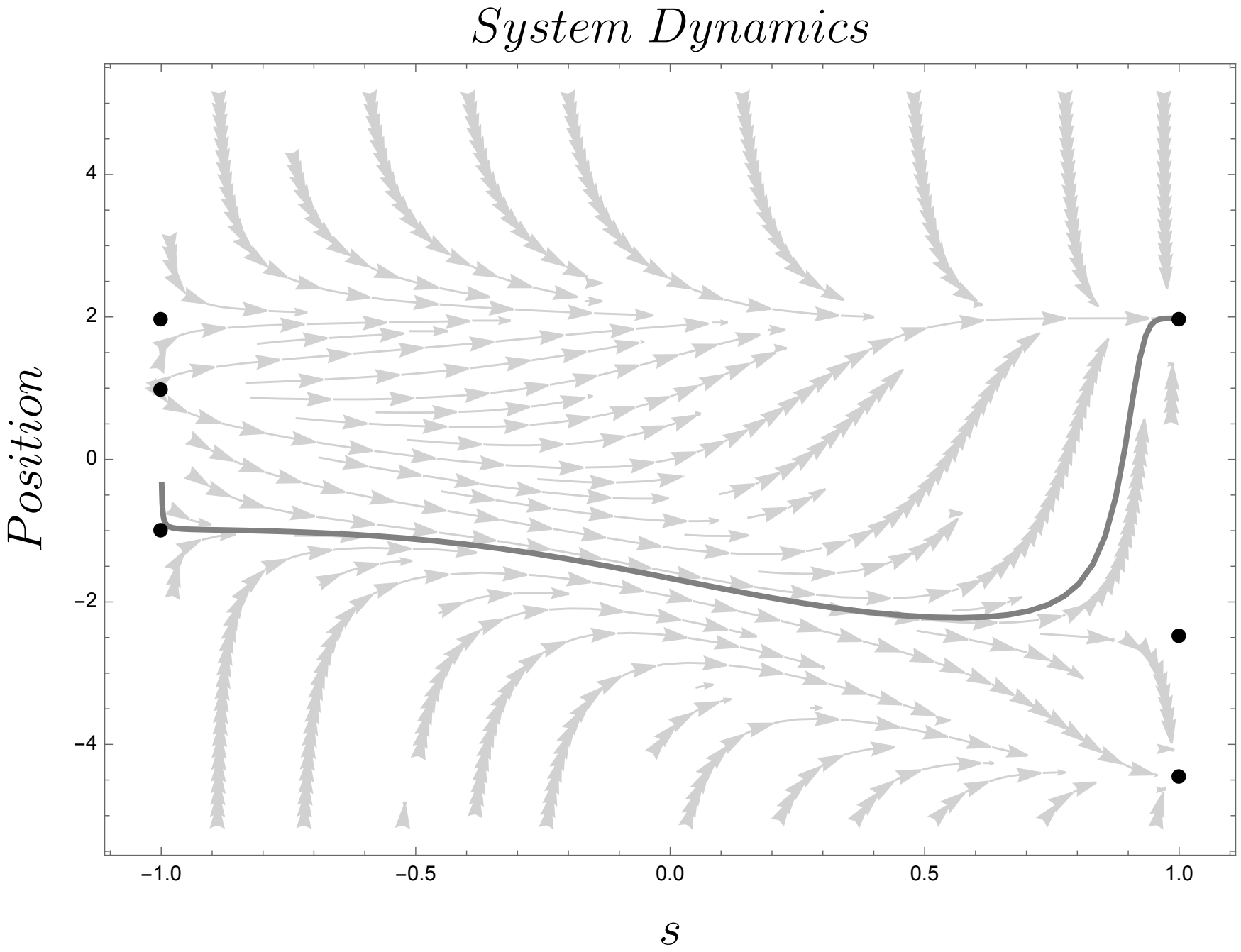
System Dynamics
Position
s
4
2
0
−2
−4
−1.0
−0.5
0.0
0.5
1.0