

Suppose that we have a two-variable dynamic system involving two stationary variables x and y . There is contemporaneous causality running from x to y , but not vice versa. The structural model is, therefore, given by

$$\begin{aligned}x_t &= \alpha_0 + \alpha_1 x_{t-1} + \theta_1 y_{t-1} + \varepsilon_t^x \\y_t &= \phi_0 + \phi_1 y_{t-1} + \delta_0 x_t + \delta_1 x_{t-1} + \varepsilon_t^y\end{aligned}$$

where the ε error terms are (homoskedastic) white noise and $\text{var}(\varepsilon_t^x) = \sigma_x^2$, $\text{var}(\varepsilon_t^y) = \sigma_y^2$, and $\text{cov}(\varepsilon_t^x, \varepsilon_t^y) = 0$. These ε terms are the “pure shocks” to x and y that are unrelated to anything in the past or anything having to do with the other variable.

1. Show that the solution of this system of equations is a VAR system that can be written

$$\begin{aligned}x_t &= \beta_{x,0} + \beta_{x,1} x_{t-1} + \gamma_{x,1} y_{t-1} + v_t^x \\y_t &= \beta_{y,0} + \beta_{y,1} x_{t-1} + \gamma_{y,1} y_{t-1} + v_t^y.\end{aligned}$$

What are the β and γ coefficients in terms of the α , θ , ϕ , and δ parameters?

2. Calculate the VAR error terms v in terms of the structural shocks ε . What is the variance of each of the v error terms and what is the covariance between them, expressed in terms of σ_x^2 , σ_y^2 , and the parameters of the model?

3. Suppose that we estimate the VAR and use the residuals \hat{v}_t^x and \hat{v}_t^y to calculate $\widehat{\text{var}}(v_t^x)$, $\widehat{\text{var}}(v_t^y)$, and $\widehat{\text{cov}}(v_t^x, v_t^y)$. Show how we can identify σ_x^2 , σ_y^2 , and δ_0 from these three parameters, and that given these identifications we can identify all of the α , θ , ϕ , and δ in the structural system from the reduced-form coefficients.

4. Without doing too much actual calculation, why would it be impossible to identify the parameters of the model if y_t appeared in the equation for x_t ?