

Reality check. Math 411

A. Compute the derivatives of the following functions at the given points as linear mappings.

1. $f: \mathbb{R}^2 \rightarrow \mathbb{R}^3$
 $(x, y) \mapsto (x^2 - y, xy, x^3 + 2xy^2)$ at $p = (1, 1)$

2. $\alpha: (-1, 1) \rightarrow \mathbb{R}^3$
 $t \mapsto (t, \cos(t), \sin(t))$ at $t = 0$

3. $g: \mathbb{R}^3 \rightarrow \mathbb{R}$
 $(x, y, z) \mapsto x + y^2 + z^3$ at $p = (1, 1, 1)$.

Solutions: 1. $f'(1,1)(x, y) = (2x - y, x + y, 5x + 4y)$.

2. $\alpha'(0)(t) = (t, 0, t)$.

3. $g'(1,1,1)(x, y, z) = x + 2y + 3z^2$.

B.

1. Let $f: \mathbb{R}^n \rightarrow \mathbb{R}^k$, $g: \mathbb{R}^k \rightarrow \mathbb{R}^m$. State the chain rule for f and g at the point $p \in \mathbb{R}^n$ in terms of Jacobian matrices and in terms of linear functions.

Solution:

$$J(g \circ f)(p) = J_g(f(p)) J_f(p)$$

$$(g \circ f)'(p) = g'(f(p)) \circ f'(p).$$

2. Suppose $w: \mathbb{R}^n \rightarrow \mathbb{R}$. Show that for all $x \in \mathbb{R}^n$,

$$\frac{d}{dt} w(tx) = \sum_{j=1}^n x_j \frac{\partial w}{\partial x_j}(tx).$$

$$\Rightarrow J_d(t) = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$$

Pf/ Define $\alpha: \mathbb{R} \rightarrow \mathbb{R}^n$ by $\alpha(t) = tx$. By the chain

rule,
$$\left[\frac{d}{dt} w(tx) \right] = J(w \circ \alpha)(t) = J_w(\alpha(t)) J_{\alpha}'(t) = J_w(tx) J_{\alpha}'(t)$$

$$= \begin{bmatrix} \frac{\partial w}{\partial x_1}(tx) & \cdots & \frac{\partial w}{\partial x_n}(tx) \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = \sum_{j=1}^n x_j \frac{\partial w}{\partial x_j}(tx). \quad \square$$

Tangent space (continued from last time)

$T_p M$ is an n -dimensional vector space $/\mathbb{R}$. This might be most easily seen via $T_p^{\text{phys}}(M)$: Choose a chart (U, h) at p .

Then

$$\begin{aligned} T_p^{\text{phys}}(M) &\longrightarrow \mathbb{R}^n & (\star) \\ v &\longmapsto v(U, h) \end{aligned}$$

gives an isomorphism of vector spaces. *Note:* the linear structure on

$T_p^{\text{phys}}(M)$ is given by $v, w \in T_p^{\text{phys}}(M) \Rightarrow \lambda v + w \in T_p^{\text{phys}}(M)$ where

$$\lambda v + w: D_p M \rightarrow \mathbb{R}^n \quad \text{by} \quad (\lambda v + w)(V, k) := \lambda v(V, k) + w(V, k).$$

The key to (\star) is that knowing $v(U, h)$ for any particular chart determines v for all charts at p .

Having fixed a chart (U, h) at p , the **standard basis** for $T_p M$ denoted $(\frac{\partial}{\partial x_1})_p, \dots, (\frac{\partial}{\partial x_n})_p$ is defined as follows:

As elements of $T_p^{\text{alg}}(M)$, i.e., as derivations, let f be a germ at p . Then

$$\left(\frac{\partial}{\partial x_i}\right)_p f := \frac{\partial}{\partial x_i} (f \circ h^{-1})(h(p))$$

for any chart (U, h) at p . Hence, $(\sum a_i (\frac{\partial}{\partial x_i})_p)(f) = \sum a_i \frac{\partial}{\partial x_i} (f \circ h^{-1})(h(p))$.

As elements of $T_p^{\text{phys}} M$, we have $(\frac{\partial}{\partial x_i})_p (U, h) = e_i = i^{\text{th}}$ standard basis

vector. Of course, the notions are compatible via our correspondence

$$T_p^{\text{phys}}(M) \longleftrightarrow T_p^{\text{alg}}(M).$$

Tangent Map / Differential

Let $f: M \rightarrow N$ be a mapping of manifolds, and let $p \in M$.
 We get an induced linear mapping

$$df_p: T_p M \rightarrow T_{f(p)} N$$

Three versions:

geometric - α a curve in M \longmapsto
 $\alpha(0) = p$

$$df_p(\alpha) := f \circ \alpha$$

$$(f \circ \alpha)(0) = f(p)$$

algebraic - $v: \mathcal{S}_p(M) \rightarrow \mathbb{R}$ \longmapsto
 derivation of germs at p

$$df_p(v): \mathcal{S}_{f(p)}(N) \rightarrow \mathbb{R}$$

$$g \mapsto v(g \circ f)$$

physical - $v \in T_p^{\text{phys}}(M)$ \longmapsto
 $v: D_p(M) \rightarrow \mathbb{R}^m$

$$df_p(v): D_{f(p)} N \rightarrow \mathbb{R}^n$$

$$(V, k) \mapsto (k \circ f \circ h^{-1})'_{k(p)}(v(u, h)),$$

(see next page)

$$\begin{array}{ccc}
 U & \xrightarrow{f} & V \\
 \downarrow h & & \downarrow k \\
 \mathbb{R}^m \cong h(U) & \xrightarrow{k \circ f \circ h^{-1}} & k(V) \subseteq \mathbb{R}^n
 \end{array}$$

← Given the chart (V, k) ,
 choose any chart (U, h) with
 $U \subseteq f^{-1}(V)$.
 ↗ open since f is cts.

Exercise: $f: \mathbb{P}^2 \rightarrow \mathbb{P}^3$
 $(x, y, z) \mapsto (x^3, y^3, z^3, xyz)$

Let $p = (1, s, t) \in U_x$. Since $f(1, s, t) = (1, s^3, t^3, st)$, consider the
 standard open set $V = \{(a, b, c, d) \in \mathbb{P}^3 : a \neq 0\}$ with $\varphi_V(a, b, c, d) = (\frac{b}{a}, \frac{c}{a}, \frac{d}{a})$.

Describe df_p as a mapping of physical tangent spaces in terms of these
 charts.

Solution: With respect to these charts, f becomes the mapping
 $\tilde{f}(u, v) = (s^3, t^3, st)$. Then $J\tilde{f}(s, t) = \begin{bmatrix} 3s^2 & 0 \\ 0 & 3t^2 \\ t & s \end{bmatrix}$.

i.e. $\varphi_V \circ f \circ \varphi_x^{-1}(st) = (s^3, t^3, st)$

So given an element of $v \in T_p^{\text{phys}} M$ that assigns the vector (v_1, v_2, v_3) to (U_x, d_x) , we have that $df_p(v)$ assigns

$$\tilde{J}\tilde{f}(s,t) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} \text{ to } (V, d_V).$$